Mechanics of Earthquakes and Faulting

Lecture 9, 25 Feb. 2021

www.geosc.psu.edu/Courses/Geosc508

- Stability Criterion
- Rate-State Friction Laws
- Changes in state via normal stress perturbations
- SHS test to measure RSF parameters
- Stability of frictional slip, Stick-slip dynamics

• Stick-slip (unstable) versus stable shear





Why is this a reasonable approach?

$$\Delta\sigma = \frac{7\pi}{16} G \frac{\Delta\overline{u}}{r}$$

How do we get at stiffness?

Relation between stress and slip on a dislocation of radius r. Therefore, the local stiffness around the slip patch is:

$$\mathsf{K} = \frac{\Delta \sigma}{\Delta \overline{u}} = \frac{7\pi}{16} \frac{G}{r}$$

That is, stiffness decreases as the patch enlarges.

Stick-slip (unstable) versus stable shear











Brittle Friction Mechanics, Stick-slip

• Stick-slip (unstable) versus stable shear



Stick-slip dynamics

$$m\ddot{x'} + \Gamma\dot{x'} + f(\dot{x'}, x', t, \theta) = F_s$$

 $m\ddot{x'} + \Gamma\dot{x'} + f(\dot{x'}, x't, \theta) = K(v_{lp} - v)t$
 $m\ddot{x'} + Fx' = K(v_{lp} - v)t$





Brittle Friction Mechanics, Stick-slip

• Stick-slip (unstable) versus stable shear





Stick-slip dynamics $m\ddot{x'} + \Gamma \dot{x'} + f(\dot{x'}, x', t, \theta) = F_s$ $m\ddot{x'} + \Gamma \dot{x'} + f(\dot{x'}, x't, \theta) = K(v_{lp} - v)t$ $m\ddot{x'} + f(x') = K(v_{lp} - v)t$ $m\ddot{x'} + Kx' = \Delta \mu N$

$$egin{aligned} x'(t) &= rac{\Delta \mu N}{K} (1 - cos \kappa t) \ v(t) &= rac{\Delta \mu N}{\sqrt{Km}} sin \kappa t \end{aligned} \quad & \kappa = \sqrt{rac{K}{m}} \end{aligned}$$

 $\left| \frac{m}{K} \right|$

 $t_r = \pi$

slip duration = rise time

Brittle Friction Mechanics, Stick-slip

• Stick-slip (unstable) versus stable shear



$$\begin{split} m\ddot{x'} + Kx' &= \Delta\mu N\\ x'(t) &= \frac{\Delta\mu N}{K}(1 - \cos\kappa t)\\ v(t) &= \frac{\Delta\mu N}{\sqrt{Km}}sin\kappa t\\ t_r &= \pi\sqrt{\frac{m}{K}}\\ \Delta x' &= \frac{2\Delta\mu N}{K} \end{split} \qquad \begin{array}{l} \text{slip duration = rise time}\\ \hline \text{total slip, particle}\\ \text{velocity, and accel. all}\\ \text{depend on friction drop}\\ (\text{stress drop}) \end{array} \end{split}$$

$$\Delta \sigma = 2(\mu_s - \mu_d)\sigma_n$$



• Stick-slip (unstable) versus stable shear







Frictional stability is determined by the combination of

- 1) fault zone frictional properties and
- 2) elastic properties of the surrounding material



Quasistatic Stability Criterion

$$K_c = \frac{\sigma_n(\mu_s - \mu_d)}{L}$$

K<K_c; Unstable, stick-slip

K > K_c; Stable sliding







1)
$$\mu(\theta, V) = \mu_o + a \ln\left(\frac{V}{V_o}\right) + b \ln\left(\frac{V_o\theta}{D_c}\right)$$

2) $\frac{d\theta}{dt} = 1 - \frac{V\theta}{D_c}$

Adhesive Theory of Fricton (Bowden and Tabor)

- Real contact area << nominal area
- Contact junctions at inelastic (plastic) yield strength
- Contacts grow with "age"
- Add: Rabinowicz's observations of static/dynamic friction
- "Static" friction is higher than "Dynamic" friction because contacts are older (larger)
- -> implies that contact size decreases as velocity increases





1)
$$\mu(\theta, V) = \mu_o + a \ln\left(\frac{V}{V_o}\right) + b \ln\left(\frac{V_o\theta}{D_c}\right)$$

2) $\frac{d\theta}{dt} = 1 - \frac{V\theta}{D_c}$

Convention is to use a, b for friction and A, B for Stress

 $\tau(\theta, v) = \tau_o + A \ln\left(\frac{V}{V_o}\right) + B \ln\left(\frac{V_o\theta}{D_c}\right)$ $A - B = \frac{\Delta\tau}{\Delta \ln V}$ Steady-state velocity strengthening if a-b > 0, velocity weakening if a-b < 0 $\mu = \frac{\Delta\tau}{\log V}$ velocity strengthening $\mu = \frac{\log V}{\log V}$

1)
$$\mu(\theta, V) = \mu_o + a \ln\left(\frac{V}{V_o}\right) + b \ln\left(\frac{V_o\theta}{D_c}\right)$$

Modeling experimental data

3) $rac{d\mu}{dt} = k(V_{lp}-V)$ Elastic Coupling

2) $\frac{d\theta}{dt} = 1 - \frac{V\theta}{D_c}$

$$V = V_o \ exp \left[\frac{\mu - \mu_o - b \ ln(\frac{V_o \theta}{D_c})}{a} \right]$$

Solve:

$$\frac{d\mu}{dt} = k \left(V_{lp} - V_o \ exp\left[\frac{\mu - \mu_o - b \ ln(\frac{V_o \theta}{D_c})}{a} \right] \right)$$
$$\frac{d\theta}{dt} = 1 - \frac{V\theta}{D_c}$$



Marone, 1998



Modeling the effect of normal force vibration 1.







Critical period is 1 to 2 sec.

Boettcher & Marone, JGR, 2004 Also, Phase lag. Friction response lags stressing. Could explain delayed triggering



No frictional response to high frequency oscillations





Empirical laws, based on laboratory friction data



Thermally-activated process

$$v = v_o \exp\left(\frac{\mu - \mu_o - b\varphi}{a}\right)$$
$$\dot{\varepsilon} = \dot{\varepsilon}_o \exp\left[-\frac{(Q - \tau_c \Omega)}{kT}\right]$$



Sheared layer of quartz particles (100-150 $\mu \rm m$), 25 MPa normal stress . Marone, 1998



Time (s)



Rate/State Friction Measuring the friction constitutive parameters

Empirical laws, based on laboratory friction data



Constitutive Modelling Rate and State Friction Law Elastic Interaction, **Testing Apparatus** $\mu(\theta, v) = \mu_0 + a \ln\left(\frac{v}{v_o}\right) + b \ln\left(\frac{v_o \theta}{D_c}\right)$ $\frac{d\theta}{dt} = 1 - \frac{v\theta}{D_c}$ $\theta_{ss} = \frac{D_c}{v}$ $\Delta \mu_{ss} = (a - b) \ln \left(\frac{v}{v_o} \right)$ $\frac{d\mu}{dt} = k' \left(v_{lp} - v \right)$

Rate/State Friction Measuring the friction constitutive parameters



Constitutive Modelling Rate and State Friction Law Elastic Interaction, **Testing Apparatus** $\mu(\theta, v) = \mu_0 + a \ln\left(\frac{v}{v_o}\right) + b \ln\left(\frac{v_o \theta}{D_c}\right)$ $\frac{d\theta}{dt} = 1 - \frac{v\theta}{D_c}$ $\theta_{ss} = \frac{D_c}{v}$ $\Delta \mu_{ss} = (a-b) \ln\left(\frac{v}{v_o}\right)$ $\frac{d\mu}{dt} = k' \left(v_{lp} - v \right)$

Rate/State Friction Measuring the friction constitutive parameters





(Marone, 1998, Nature)



 $d\theta/dt = -V \theta/D_c \ln(V \theta/D_c)$

Elastic Coupling $d\mu/dt = k(V_{p} - V)$ The rate of frictional healing depends on the rate of shearing (Marone, 1998, *Nature*) Rate State Friction Laws predict this behavior



2015)

Figure 13 Numerical simulations of SHS tests showing healing and relaxation predicted by the RSF laws and elastic interaction. Inset to (a) shows details of a single simulation for which steady sliding is prescribed prior to a hold that begins at a normalized slip of 0 (the friction level is arbitrary and chosen as 0). The RSF laws predict that friction decreases during the hold due to creep and elastic interaction. Each point in the main panels shows results from a simulation. Four cases are shown corresponding to two velocities for each of the friction laws. Panels (a) and (b) show variations in the coefficient of friction. The same results are shown in nondimensional form in panels (c) and (d). Both laws show that healing and relaxation scale with loading rate and hold time, consistent with the experimental results. Simulations were carried out using the constitutive parameters given in the figure.



Loading rate effect on frictional healing is due to a combination of the friction direct effect and state evolution

$$egin{aligned} \mu(heta,V) &= \mu_o + a \, ln \left(rac{V}{V_o}
ight) + b \, ln \left(rac{V_o heta}{D_c}
ight) \ &rac{d heta}{dt} = 1 - rac{V heta}{D_c} \ &rac{d\mu}{dt} = k(V_{lp} - V) \end{aligned}$$

shs test: 1 μm/s 10 μm/s Phase Plane Plots

Loading rate effect on frictional healing is due to a combination of the friction direct effect and state evolution

$$\mu(\theta, V) = \mu_o + a \ln\left(\frac{V}{V_o}\right) + b \ln\left(\frac{V_o\theta}{D_c}\right)$$

$$rac{d heta}{dt} = 1 - rac{V heta}{D_c}$$
 $rac{d\mu}{dt} = k(V_{lp} - V)$

Slide-hold-slide

Slip-reload-slip

Earthquake-interseismic healing and reloading-earthquake

The full seismic cycle of stickslip, frictional restrengthening, and interseismic reloading

Marone and Saffer, 2013 Figure 4

Time dependent yield strength:

$$\mu = \frac{\tau}{\sigma_n} = \frac{S}{\sigma_y}$$

Dieterich and Kilgore [1994]

Time dependent growth of contact (acyrlic plastic)- true static contact

$$\mu = \frac{\tau}{\sigma_n} = \frac{S}{\sigma_y}$$

$$\sigma_{y} = \sigma_{o} + f(t)$$

Modified from Beeler, 2003

How do fault/frictional surfaces heal (regain strength) after failure?

Earthquakes & Fault Mechanics: seismic cycle, fault reactivation. (friction and stick slip: doors, windows, machines, ships in dry dock, dancers...)

Time dependence of "static" friction Aging of frictional contacts

C. A. Coulomb (1736-1806)

Table 9.1

	T (time of repose, min)	A+mT [*] (static friction force, lbf)
I ^{cre} observation	0	A=502
II ^c	2	790
IIIc	4	866
IV ^e	9	925
V ^e	26	1,036
VI ^c	60	1,186
VII ^c	960	1,535

static friction of two pieces of well-worn oak lubricated with tallow.

Time dependence of "static" friction Aging of frictional contacts

C. A. Coulomb (1736-1806)

Table 9.1 Т $A + mT^{\mu}$ (time of repose, min) (static friction force, lbf) Icre observation 0 A = 502IIc 790 IIIc 866 IV 925 Vc 26 1,036 VIc 60 1,186 VII 960 1,535

static friction of two pieces of well-worn oak lubricated with tallow.

Time dependence of friction in rocks; Macroscopic frictional aging

Frictional Healing Stressed aging

Steady state friction & the rate of healing vary with sliding velocity

Load point

Fault

surface

Angular quartz particles (100-150 μ m), 3 mm thick, 25 MPa normal stress. Marone, Nature, 1998

Marone, Nature, 1998

Frictional aging. How does it work? What is the role of shear velocity?

Chemically-Assisted Frictional Aging; Creep at Adhesive Contact Junctions

In-situ Particle Comminution; Production of Fresh Surface Area

Frye and Marone, JGR 2002

Granular quartz

Hydrolytic Weakening causes enhanced rate of strengthening

Chemically-Assisted Frictional Aging; Creep at Adhesive Contact Junctions

Hydrolytic Weakening causes enhanced rate of strengthening, but base level frictional strength is unchanged

Frye and Marone, JGR 2002

Solid Surfaces: Base level of frictional strength decreases with increasing water content (cf. Dieterich & Conrad, 1984) Granular Materials: Frictional strength is independent of water content

Interpretation: Contact junctions subject to time dependent strengthening or growth, which inhibits sliding, but particle rolling is not affected by these factors.

Frye and Marone, JGR 2002

Empirical laws, based on laboratory friction data

Measuring the velocity dependence of friction

Frictional Instability Requires (a-b) < 0

Constitutive Modelling
Rate and State Friction Law
Elastic Interaction, Testing Apparatus

$$\mu(\theta, v) = \mu_0 + a \ln\left(\frac{v}{v_o}\right) + b \ln\left(\frac{v_o \theta}{D_c}\right)$$

$$\frac{d\theta}{dt} = 1 - \frac{v \theta}{D_c}$$

$$\theta_{ss} = \frac{D_c}{v}$$

$$\Delta \mu_{ss} = (a-b) \ln\left(\frac{v}{v_o}\right)$$

$$\frac{d\mu}{dt} = k' (v_{lp} - v)$$

Results: Velocity stepping Measuring the velocity dependence of friction

Frictional Instability Requires K < K_c

$$K_c = \frac{\sigma_n(b-a)}{D_c}$$

This example shows steady-state velocity strengthening: (a-b) > 0

Stresses v. Unstressed Aging

100 s holds, Healing rate varies systematically with shear stress

Karner & Marone (GRL 1998 JGR 2001)